EE653 - Coding Theory

Lecture 1: Introduction & Overview

Dr. Duy Nguyen



SAN DIEGO STATE UNIVERSITY

Leadership Starts Here

Outline



2 Introduction to Coding Theory

3 Examples of Error Control Coding



Administration

Hours and Location

- Lectures: MW 4:00pm 5:15pm
- Location: P-148
- Office hours: MW 2:00pm 3:00pm or by email appointments
- Course webpage:

http://engineering.sdsu.edu/~nguyen/EE653/index.html

Instructor:

- Name: Dr. Duy Nguyen
- Office: E-408
- Phone: 619-594-2430
- Email: duy.nguyen@sdsu.edu
- Webpage: http://engineering.sdsu.edu/~nguyen
- Teaching Assistant: N/A

Syllabus

Prerequisite

- EE 558 Digital Communications
- Knowledge of MATLAB programming

References

- 1. Shu Lin and Daniel J. Costello, Jr., *Error Control Coding: Fundamentals and Applications*, 2nd Ed., Prentice Hall, 2004.
- 2. B. Sklar, *Digital Communications: Fundamentals and Applications*, 2nd Ed., Prentice Hall, 2001.
- 3. J. Proakis, *Digital Communications*, 4th Ed., McGraw-Hill, 2000.

Assessments

- Assessments: 20% Homework, 15% Quiz, 15% Midterm Exam, 20% Project, and 30% Final Exam (Open-Book)
- Homework assignments: Bi-weekly, Total: 5. Late submission: maximum 1 day, 20% score deducted
- Research Project: In-depth study or original research topic
 - Project Proposal: 1 page (%5)
 - Project Report: 5-7 pages (double-column) (%10)
 - Presentation: 15 minutes End of semester (%5)
- Midterm: Monday, Mar 06
- Final: Monday, May 08 at 15:30 17:30
- Grades:

90–100	A/-
75–89	B/\pm
60–74	C/\pm
50–59	D/+

Schedule

Week	Day	Task	Week	Day	Task
1	М		9	М	
Jan 16	W	First day of class	Mar 13	W	
2	М		10	М	HW4 out, HW3 due
Jan 23	W		Mar 20	W	
3	М	HW1 out	BREAK	М	Spring break
Jan 30	W		Mar 27	W	Spring break
4	М		11	М	Quiz 2
Feb 6	W		Apr 3	W	
5	М	HW2 out, HW1 due	12	М	HW5 out, HW4 due
Feb 13	W		Apr 10	W	
6	М	Quiz 1	13	М	Quiz 3
Feb 20	W		Apr 17	W	
7	М	HW3 out, HW2 due	14	М	HW5 due
Feb 27	W		Apr 24	W	
8	М	Midterm Exam	15	М	Project presentation
Mar 6	W	Project proposal due	May 1	W	Final Report due

Topics to Cover

- Mathematical background
 - Related background on Abstract Algebra
- Linear block codes
 - Hamming codes
 - Reed-Muller codes
- Cyclic codes
 - Cyclic codes
 - BCH codes
 - Reed-Solomon codes
- Convolutional codes
- Advanced Topics: Turbo codes, Low-Density Parity Check (LDPC) codes, trellis coded modulation (TCM), bit-interleaved coded modulation (BICM)

Outline



Introduction to Coding Theory

3 Examples of Error Control Coding



What is Coding for?



- Source Coding
 - The process of compressing the data using fewer bits to remove redundancy
 - Shannon's source coding theorem establishes the limits to possible data compression: entropy
- Channel Coding or Error Control Coding
 - The process of adding redundancy to information data to better withstand the effects of channel impairments
 - Shannon-Hartley's capacity theorem establishes the limits for data transmission with an arbitrary small error probability

What is Source Coding?

- Forming efficient descriptions of information sources
- Reduction in memory to store or bandwidth resources to transport sample realizations of the source data
- Discrete sources: entropy to define the average self-information for the symbols in an alphabet

$$\mathbf{H}(X) = -\sum_{j=1}^{N} p_j \log_2(p_j)$$

• Maximum entropy with equal probability 1/N for all symbols

$$0 \le \mathrm{H}(X) \le \log_2(N)$$

- Compress source signals to the entropy limit
- Examples: entropy of binary sources

What is Error Control Coding?

• Coding for reliable digital storage and transmission

"The fundamental problem of communication is that of reproducing at one point either exactly or approximately a message selected at another point." (Claude Shannon 1948)

- Proper encoding can reduce errors to any desired level as long as the information rate is less than the capacity of the channel
- What is Error Control Coding?
 - Adding redundancy for error detection and/or correction
 - Automatic Repeat reQuest (ARQ): error detection only easy and fast with parity check bits. If there is an error, retransmission is necessary (ACK vs NAK)
 - Forward ECC: both error detection and correction more complicated encoding and decoding techniques

Focus of this course: channel encoding and decoding! Introduction to Coding Theory

Communication Channel

Physical medium: used to send the signal from TX to RXDescribe the transition probability from input to output

$$x \longrightarrow \begin{array}{c} n \\ \downarrow \\ P_{Y|X}(y|x) \end{array} \longrightarrow y$$

 $\longrightarrow 0$

_____→ 1

Noiseless binary channel: input is reproduced exactly at output





Channel Capacity

• Example of AWGN channel: y = x + n, $n \sim \mathcal{N}(0, N)$, $\mathbb{E}[|x|^2] = S$

Mutual information

$$\mathbf{I}(x;y) = \mathbf{H}(y) - \mathbf{H}(y|x)$$

Capacity of a channel

$$C = \max_{p(x_i)} \mathbf{I}(x; y)$$

Gaussian distribution has the highest entropy

1

$$\mathbf{H}(y|x) = \mathbf{H}(n) = \frac{1}{2} \log \left[2\pi eN\right]$$

• H(y) is maximum if y is Gaussian $\rightarrow x$ is also Gaussian

$$\mathbf{H}(y) = \frac{1}{2} \log \left[2\pi e(S+N) \right]$$

Shannon-Hartley theorem on channel capacity with Gaussian input

$$C = \frac{1}{2} \log \left(1 + \frac{S}{N} \right)$$
 nats/s/Hz

Outline



2 Introduction to Coding Theory





Example 1: Repetition Code

- **Repetition code**: Repeat each bit (n-1) times
- Code rate 1/n, denoted as R_n
- Encoding rule for R_5 code:
 - ▶ $0 \rightarrow 00000$
 - ▶ $1 \rightarrow 11111$
- Decoding rule:
 - Majority decoding rule: choose bit that occurs more frequently
- Example with R₅ code: We have information bits 10. After encoding, we have 1111100000. If 0110111000 is received (some bits are in error):
 - We first decode **01101** to 1
 - ▶ We then decode 11000 to 0
 - Decoded bits: 10

How Good Is Repetition Code?

- Without repetition code, assume the probability of error is p
- With R_n code, the probability of error is:

$$P_E = \sum_{i=(n+1)/2}^{n} \binom{n}{i} p^i (1-p)^{n-i}$$

- Repetition is the simplest code: Is it a good code?
- With $p = 10^{-1}$ and R_3 code, overall error P_E is 2×10^{-2}
- Not good if n is small. If n is large: Overhead burden

How Good is Repetition Code?



Source: David J. C. MacKay, Information Theory, Inference, and Learning Algorithms.

How Good is Repetition Code?



Source: David J. C. MacKay, Information Theory, Inference, and Learning Algorithms.

Example 2: Cyclic Redundancy Check (CRC)

- Check values are added to information. If the check values do not match, re-transmission is requested
- CRC: Used for error detection, not correction
- Simple to implement in binary hardware, easy to analyze mathematically, and particularly good at detecting common errors
- Commonly used in digital networks and storage devices; Ethernet and many other standards
- CRC is a special case of Cyclic Codes
- In this course, most of the time, the focus is on Forward Error Correction (FEC): a one-way system employing error-correcting codes that automatically correct errors detected at the receiver

What is a "Good" Code?

■ For a bandwidth W, power P, Gaussian noise power spectral density N₀, there exists a coding scheme that drives the probability of error arbitrarily close to 0, as long as the transmission rate R is smaller than the Shannon capacity limit C:

$$C = W \log_2 \left(1 + \frac{P}{W N_0} \right) \quad \text{(bits/s)}$$

- Consider the normalized channel capacity (spectral efficiency) $\eta = C/W(\text{bits/s/Hz})$ with $P = CE_b$, where E_b : energy per bit: $\eta = \frac{C}{W} = \log_2\left(1 + \frac{C}{W}\frac{E_b}{N_0}\right)$
- Then we have

$$\frac{E_b}{N_0} = \frac{2^\eta - 1}{\eta}$$

 Claude E. Shannon, A Mathematical Theory of Communication. Bell System Technical Journal, 27, 379–423 & 623–656, 1948.

Capacity Approaching Coding Schemes

- If R > C: no way for a reliable transmission
- \blacksquare If $R \leq C:$ the results of the theorem were based on the idea of random coding
 - The theorem was proved using random coding bound
 - Block length must goes to infinity
- No explicit/practical coding scheme was provided
- A holy grail for communication engineers and coding theorist
 - Finding a scheme with performance close to what was promised by Shannon: Capacity-approaching schemes
 - Complexity in implementation of those schemes
- High performing coding schemes only found very recently!

A Brief History of Error Control Coding

- Linear block codes: Hamming code (1950), Reed-Muller code (1954)
- Cyclic codes: BCH code (1960), Reed-Solomon (1960)
- LDPC, 1963
- TCM, 1976 & 1982
- Turbo codes, 1993
- BICM, 1996
- The rediscovery of LDPC, 1996
- Fountain codes: LT code (2003), Raptor code (2006)
- Polar code, 2009

Outline

- 1 Course Information
- Introduction to Coding Theory
- 3 Examples of Error Control Coding



Review of Digital Communications

Digital Communication System



Digital Communication System

- Information $\mathbf{u} = 1001$; Using repetition code R_3 , we have coded bits $\mathbf{v} = 111000000111$
- Now we can use BPSK modulation scheme:

Bit 0:
$$-\sqrt{E_s}\sqrt{\frac{2}{T_b}}\cos\left(2\pi f_c t\right)$$

Bit 1: $+\sqrt{E_s}\sqrt{\frac{2}{T_b}}\cos\left(2\pi f_c t\right)$

- Baseband model r[m] = x[m] + w[m], with $x[m] = \pm \sqrt{E_s}; w[m] \sim \mathcal{N}(0, N_0/2)$: AWGN
- What can we do with r[m]? Hard-decision decoding and soft-decision decoding

Digital Communication System

- If hard-decision decoding, the uncoded bit error probability is $p = \mathcal{Q}\left(\sqrt{2E_s/N_0}\right)$. We will then have a binary symmetric channel (BSC) with transition probability p
- Here, Q(x) is the complementary error function, defined as

$$\mathcal{Q}(x) = \frac{1}{2\pi} \int_x^\infty e^{-y^2/2} dy$$

- Given p, we should be able to calculate the bit error probability of our information sequence
- Soft-decision decoding: offers significant performance. We will talk later on about it

Maximum Likelihood Decoding



- \blacksquare Information ${\bf u};$ coded information or coded bits ${\bf v}$
- After modulation, we have transmitted signals x. For the moment, let's assume we use BPSK so that length of v and x are the same
- At the receiver, we receive ${\bf r}.$ From ${\bf r},$ the decoder needs to produce an estimate $\hat{{\bf u}}$
- Equivalently, since there is one-to-one correspondence between information sequence u and coded sequence v, the decoder can produce an estimate \hat{v}

Maximum Likelihood Decoding

- Clearly, $\hat{\mathbf{u}} = \mathbf{u}$ if and only if $\hat{\mathbf{v}} = \mathbf{v}$.
- A decoding rule is a strategy for choosing an estimated of v for each possible received sequence r, e.g., the hard decision decoding rule.
- Given that **r** is received, the *conditional error probability* of the decoder is defined as:

$$P(E|\mathbf{r}) \triangleq P\left(\hat{\mathbf{v}} \neq \mathbf{v}|\mathbf{r}\right)$$

• The error probability of the decoder is then given by:

$$P(E) = \sum_{\mathbf{r}} P(E|\mathbf{r}) P(\mathbf{r})$$

Maximum Likelihood Decoding

- $P(\mathbf{r})$ is independent of decoding rule, since \mathbf{r} is produced prior to decoding. Hence, an optimal decoding rule, that is, one that minimize P(E) must minimize $P(E|\mathbf{r}) = P(\hat{\mathbf{v}} \neq \mathbf{v}|\mathbf{r})$ for all \mathbf{r} .
- Now, note that minimizing $P(\hat{\mathbf{v}} \neq \mathbf{v} | \mathbf{r})$ is equivalent to maximizing $P(\hat{\mathbf{v}} = \mathbf{v} | \mathbf{r})$. Therefore, an optimal decoding rule is to choose a codeword \mathbf{v} that maximizes

$$P(\mathbf{v}|\mathbf{r}) = \frac{P(\mathbf{r}|\mathbf{v})P(\mathbf{v})}{P(\mathbf{r})}$$

 If we assume all information sequences u are equally likely, it would be the same for all coded sequences v. As such, P(v are the same for all v. It means that for an optimal decoding rule, we need to find a codeword v to maximize P(r|v): Maximum Likelihood Decoding (MLD) rule.

MLD with DMC and BSC

- If we assume channel is discrete and memoryless channel (DMC), i.e., each received symbol r_i depends only on the corresponding transmitted symbol x_i (or v_i), we have $P(\mathbf{r}|\mathbf{v}) = \prod_i P(r_i|v_i)$
- So MLD is equivalent to maximize the log-likelihood function:

$$\log P(\mathbf{r}|\mathbf{v}) = \sum_{i} \log P(r_i|v_i)$$

i.e, we need to choose ${\bf v}$ to maximize the above sum

Now, we consider a special case of BSC channel, i.e., **r** is a binary sequence that may differ from transmitted sequence **v** in some positions owning to the channel noise. For this BSC, assume when $r_i \neq v_i$, $P(r_i|v_i) = p$. Of course, when $r_i = v_i$, $P(r_i|v_i) = 1 - p$

MLD with DMC and BSC

- Now, let d(r, v) be the distance between r and v, that is, the number of positions in which r and v differ. Since they are binary sequences, this distance is called *Hamming distance*.
- Assume a block length of *n*, we then have:

$$\sum_{i} \log P(r_i|v_i) = d(\mathbf{r}, \mathbf{v}) \log p + [n - d(\mathbf{r}, \mathbf{v})] \log(1 - p)$$
$$= d(\mathbf{r}, \mathbf{v}) \log \frac{p}{1 - p} + n \log(1 - p)$$

So what is MLD rule now?